

# Kowin S. Shi

Website: [kowinshi.me](http://kowinshi.me) Github: [github.com/SkookumAsFrig](https://github.com/SkookumAsFrig)  
Cell: (909) 667-9419 Email: [kowinshi@hotmail.com](mailto:kowinshi@hotmail.com)

## EDUCATION

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**Cornell University**, College of Engineering, Ithaca, NY

**Master of Engineering, Electrical and Computer Engineering**

Aug. 2019 - May 2020

Focus: Robotics and Controls; GPA: 4.20

**Bachelor of Science, Mechanical Engineering**

Aug. 2015 - May 2019

Minor: Electrical and Computer Engineering

Honors: *Cum Laude*; Major GPA: 4.03

## PROFESSIONAL EXPERIENCE

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**Blue River Technology (John Deere)**, Santa Clara, CA

*Mechatronics Engineer II*

Feb 2023 – Present

- Design, deploy and debug robots in remote, harsh environments
- Develop and negotiate product + engineering requirements with customers
- Specializations: Electro-Mechanical Co-Design, System Architecture, Automotive Electrical Harness, Rigid-Flex PCB for High-Speed Signal/Power, Power Electronics, Fusing, Multiphysics CAE, GD&T, Shock/Vibe Reliability, EMI/EMC Compliance

**Amazon Prime Air**, Seattle, WA

*Hardware Development Engineer II*

July 2022 – Feb 2023

- Developed high power propulsion systems and precision robotics for wind tunnel testing

**Aurora Innovation Inc.**, Pittsburgh, PA

*Hardware Engineer II*

Jan 2021 – July 2022

- Continued work from Uber ATG acquisition, creating some of the most powerful, reliable and scalable computer solutions in the self-driving space

**Uber Advanced Technologies Group**, Pittsburgh, PA

*Autonomy Hardware Engineer*

July 2020 – Jan 2021

*Hardware Engineering Intern*

2019

**Tesla, Inc.**, Palo Alto/Fremont, CA

*Engineering Intern, Power Electronics*

2018

- Developed automated tester for Model S and X high voltage junction box, deployed at contract manufacturer

*Engineering Intern, Drive Systems (Motor Design Team)*

2017

- Designed Model 3, S and X motor components, supported manufacturing processes with testing and tooling designs

**GAC Automotive Engineering Institute**, Guangzhou, China

2016

*Prototype Engineering Intern*

## SPECIALIZED SKILLS

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**Engineering Programs:** CATIA, 3DX/ENOVIA, ANSYS, Solidworks/EPDM, Inventor, ROS, Gazebo, Git, Altium Designer, Kicad, RapidHarness, Enterprise Harness, Intel Quartus Prime, Xilinx Vivado, Siemens NX, Fusion 360, RSLogix, AutoCAD Electrical

**Programming Languages:** Python, C/C++, CUDA, Assembly, Verilog/System Verilog, MATLAB, G-code, Java, PLC Ladder Logic

**Fabrication Skills:** PCBA bring-up. Operation of lathes and mills. Utilization of G-code and CAM for CNC machining. TIG welding, composites manufacturing, 3D printing and soldering. Application of geometric dimensioning and tolerancing.

**Foreign Languages:** Mandarin (native proficiency), Spanish (limited working proficiency)

**Professional Certifications:** Lean Six Sigma Green Belt, OSHA 10 Hour Construction

## ENGINEERING PROJECTS

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- Visit [kowinshi.me](http://kowinshi.me) for list of projects that include robotics, FPGA, control systems, power electronics and more.

## RESEARCH EXPERIENCE

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**Collective Embodied Intelligence Lab**, Cornell University, Ithaca, NY

2020

*Independent Researcher*

- Formica Forma: Explorations in Insect-Robot Collaboration for Emergent Design and Manufacturing. *Proceedings of the 40th Annual Conference of ACADIA, Distributed Proximities*, 310–319. <https://doi.org/10.3929/ETHZ-B-000530230>
- Developed and evaluated novel method of manufacturing, by UV-light guidance of ant tunneling with a robot arm

## TEAM EXPERIENCE

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**Formula SAE Racing Team**, Cornell University, Ithaca, NY

2015 – 2019

*Suspension and Electrical Team Member*

**Resistance Racing Shell Eco Marathon Team**, Cornell University, Ithaca, NY

2016 – 2018

*Aerodynamics/Vehicle Body Sub-team Lead*